

LS LIDAR PRODUCT GUIDE

AGV & ROBOTS APPLICATIONS





Service robots



























AGV

















CX Series 32 / 20-Channel LiDAR



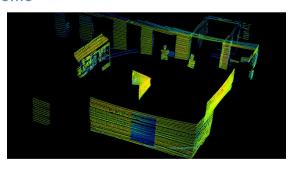
Abstract

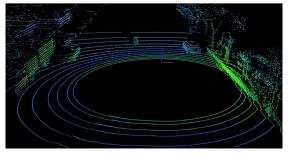
CX Series 32 / 20 channel LiDAR achieves 360° 3D high-speed scanning with 3 20-beam laser, measurement range up to 200 m, ± 3 cm accuracy, minimum vertical angle resolution up to $0.33^\circ(C32)$ /1°(C20), C32 widely used in autonomous vehicle, ADAS, smart transportation, service robots, logistics, surveying and mapping, security and so on. The C20 channel LIDAR can detect moving targets on large-area scenes with 16-beam laser scanning down, which widely used in V2X , smart transportation

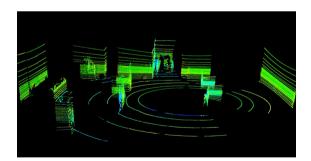
Features

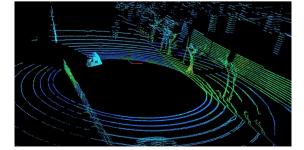
- High point density, capability of generating approximately 640,000 point per second (C32) / 400,000 point per second (C20).
- Wide field of view, with 360° horizontal FOV and 32° vertical FOV.
- The C32 Vertical angular resolution up to 0.33°, focused on front area data acquisition.

Demo











Model		C32		C20	
Channel		32		20	
Measurement Technique		Time of Flight(TOF)			
Wavelength		905nm			
Laser Product Classification		Class 1 Eye-safe/ IEC 60825-1:2007 & 2014			
Measurement Range		70m / 120m /150m			
Ranging Accuracy		±3cm			
Data Points Generated		640,000points per second		400,000points per second	
Rotation Rate		5Hz , 10Hz , 20Hz			
Field of View (FOV)	Horizontal	360°			
	Vertical	-16°~ 15°	-18°~ 14°	-16°~ 3°	
Angular	Horizontal	5Hz: 0.09° / 10Hz: 0.18° / 20Hz: 0.36°			
Resolution	Vertical	0.33° / 1°			
Operating	g Voltage	9V~ 36VDC			
Operating Temperature		-20°C ~ 60°C (Customized up to -40°C)			
Communication Interface		Ethernet , PPS			
Shock Test		500m/sec², last11ms			
Vibration		5Hz-2000Hz,3G rms			
IP		IP 67			
Dimension (D·H)		Ф120*110mm			
Weight		1600g			



CX Series 16-Channel LiDAR



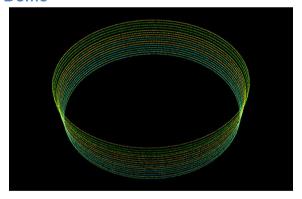
Abstract

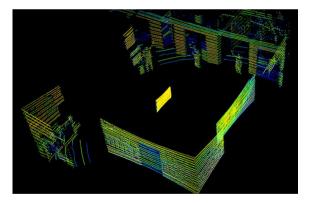
CX Series 16 channel LIDAR achieves 360 ° 3D high-speed scanning with 16-beam laser, measurement range up to 200 m, ±3cm accuracy, up to 1.33° vertical angle resolution, widely used in autonomous vehicle, ADAS, smart transportation, service robots, logistics, surveying and mapping, security and so on.

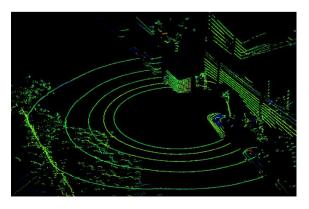
Features

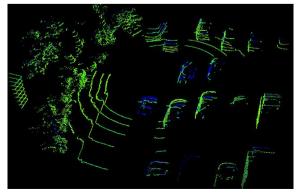
- High point density, capable of generating approximately 320,000 3D point cloud coordinates per second
- Wide field of view, with 360°horizontal FOV and 32°vertical FOV.
- Compact size and light weight

Demo









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Model		C16			
Channel		16			
Measurement Technique		Time of Flight (TOF)			
Wavelength		905nm			
Laser Product Classification		Class 1 Eye-safe/ IEC 60825-1:2007 & 2014			
Measurement Range		70m / 120m / 150m			
Ranging Accuracy		±3cm			
Data Points Generated		320,000 points per second			
Rotation Rate		5Hz,10Hz,20Hz			
Field of	Horizontal	360°			
View (FOV)	Vertical	-15°~ 15°	-14°~ 16°	-15°~ 15°	-10°~ 10°
Angular	Horizontal	5Hz: 0.09° / 10Hz: 0.18° / 20Hz: 0.36°			
Resolution	Vertical	2°		2°	1.33°
Operating Voltage		9V~ 36VDC			
Communication Interface		Ethernet , PPS			
Operating Temperature		-20°C ∼ 60°C (Customized up to -40°C)			
Shock Test		500m/sec², last11ms			
Vibration		5Hz-2000Hz,3G rms			
IP		IP 67			
Dimension (D·H)		120*110mm 102*78mm			'8mm
Weight		1600g 1000g			00g



N301 Series TOF Navigation & Obstacle Avoidance LiDAR



Abstract

The N301 series of LiDAR adopt the TOF principle, with a 360° scanning and measurement range is up to 150m. The ranging accuracy is ±3cm, which can identify the position, size and moving direction of the detected object in real time.

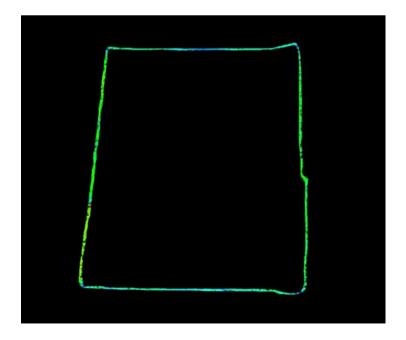
Features

- 360° FOV, long measurement range
- The minimum angular resolution reaches 0.18°, ensuring measurement data accurately and stably.
- Configuring an Ethernet interface for high-speed data transmission

Application field

- ADAS
- High-precision Autonomous positioning and navigation of service robots
- AGV navigation and obstacle avoidance, regional security

Demo





Model	N301	N301HA			
Wavelength	905nm				
Laser Product Classification	Class 1Eye-safe /IEC 60825-1:2007&2014				
Data content	Distance /Angle				
Measurement Range	10m/30m/50m/100m				
Ranging Accuracy	±3cm				
Positioning accuracy	±1cm				
Scanning angle	360°				
Rotation Rate	10Hz / 20Hz				
Pulse Repetition Rate	20,000 points per second	300,000 points per second			
Angular Resolution	20Hz:0.36° 10Hz:0.18°	20Hz:0.024° 10Hz:0.012			
Operating Voltage	9V ~ 36VDC				
Operating Temperature	-20°C ~ 60°C				
Motor	Built-in Brushless Motor				
Communication Interface	Ethernet				
Weight	420g(±20g)				
Dimension (D·H)	Ф80*79.1mm				



N401 Series TOF Navigation Obstacle Avoidance LiDAR



Abstract

The N401 series of LiDAR adopt the TOF principle, with a 360°scanning and measurement range is up to 150m. the distance accuracy can reach ±1cm base on reflector. Widely used in robot, AGV High-precision positioning and navigation, obstacle avoidance.

Specifications

Model	N401	N401HA		
Wavelength	905nm			
Laser Product Classification	Class 1Eye-safe /IEC 60825-1:2007&2014			
Data content	Distance /Angle /Reflectivity			
Measurement Range	10m/30m/50m/100m			
Ranging Accuracy	±3cm			
Positioning accuracy	±1cm			
Scanning angle	360°			
Rotation Rate	10Hz / 20Hz			
Pulse Repetition Rate	20,000 points per second	300,000 points per second		
Angular Resolution	20Hz:0.36° 10Hz:0.18°	20Hz:0.024° 10Hz:0.012		
Operating Voltage	9V ~ 36VDC			
Operating Temperature	-20°C ~ 60°C			
Motor	Built-in Brushless Motor			
Communication Interface	Ethernet			
Weight	420g(±20g)			
Dimension (D·H)	Ф80*79.1mm			



W Series TOF Anti-collision LiDAR



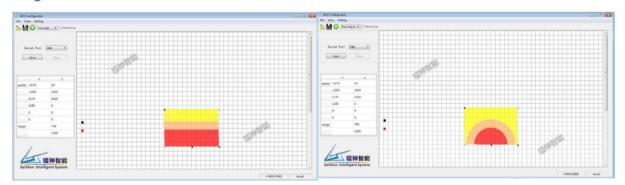
Abstract

LeiShen W series Anti-collision Laser Scanner is mainly applied to performs collision avoidance and area detection for AGV, RGV, Robot, ect. There are 15 field sets to be chosen and finally output with signals of switching values and point cloud

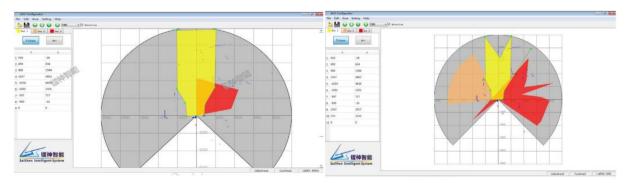
Features

- Simultaneous output of switch and point cloud data
- Flexible configuration to detection areas.
- With 15 detection areas selectable and two detecting mode: independent type and correlation type

Regional association



Regional independent





Model	W Series		
Output	Switching Value and Point Cloud Data/ Switching Value		
Scanning angle	270°		
Rotation Rate	10 Hz		
Measurement Range	5m/10m/30m		
Angular Resolution	1° / 0.36°		
Monitoring area	Correlation/ Independent		
Operating Voltage	9V~28VDC		
Operating Temperature	-20°C ~ 60°C		
Shock Test	500m/sec², last11ms		
Vibration	5Hz-2000Hz,3G rms		
IP	IP 67		
Weight	397g		
Interface	NPN , PNP		
Dimension (D·H)	Ф80*77.3mm		



LS01 Series 360°Triangular LiDAR



Abstract

LS01 series LiDAR is a 2D LiDAR developed by Leishen. This series LiDAR can do 360° 2D scanning to generate spatial point cloud map .

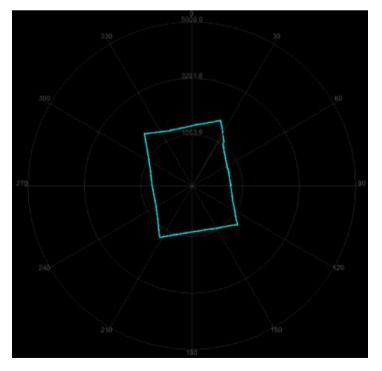
Features

- Triangulation principle, Cost-effective
- Max light intensity up to 20,000lux
- Compact, low power consumption, durable

Applications

- Robotic self-navigation and positioning
- AGV self-navigation and positioning

Demo (LS01B)



LS02 Series Solid State LiDAR





LS02A/LS02B

LS02C/LS02D

ABSTRACT

LS02A sensor is a low-cost 2D Solid LIDAR developed by LeiShen Intelligent System Co., Ltd. It performs 86 degree laser scanning and ranging with structured light through a semiconductorlaser. Comparing with rotating sensors, it has longer service lifetime, higher stability, and lower cost.

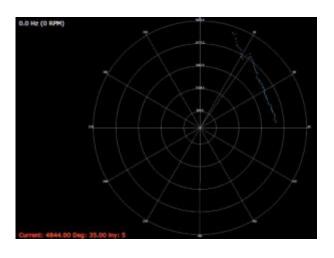
FEATURES

- Solid State, High reliability, Long service lifetime.
- Light and small, 50g weight at most.
- High Accuracy, Low-cost.
- Strong anti-disturbance capacity

Application

- Navigation & anti-collision of service robot, Cleaning robot, AGV.
- Anti-collision of ADAS.

PC Software Display (take LS02A as example)



Specification

Model	LS02A	LS02B	LS02C	LS02D	
FOV	86°				
Detection Range	0.1~4m(under 70% reflectivity)				
Angular Resolution	1°	0.5°	1°	0.5°	
Distance Tolerance	≤1.5% of	distance	≤1.5% of Ranging		
Scan rate	10Hz				
Weight	50g				
Size(W×L×H)	40×30×	65mm	40×37×45mm		
Dara output					



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